

DESIGN CODE: ISO 13628-8 NOTE: 2 **TECHNICAL CLASSIFICATION:** 008-Actuation Article Type: 8.01. ISO 1 to 4 Actuation Main Group: Intermediate Group: 8.44.01. Tool 8.44.114.02. Intervention Sub Group: NOTE: 3 INTERFACE INFORMATION

TERFACE INFORM	MATION:
essure Rating Bar:	3000m
sign Water Depth:	N/A
aterial:	Hard Anodize Aluminium
eight in Air:	55 kg
lume:	149,36 dm^3
rface Area:	242380 cm^2
draulic:	N/A
echanical:	N/A
ectrical:	110-250 VAC / 145-350 VDC
m. & Protocol:	RS232

NOTE: 4

ADDITIONAL INFORMATION: Complete Class 1-4 Electrical Torque Tool System prepared for offshore use and operation, includes El Torque Tool, Control Canister, cables, class 2 and 4 sockets and control pc.

The Blue Logic Class 1-4 Electrical Torque Tool (ELTT) is a module based, compact, flexible and robust precision tool for operation in all Subsea and ROV applications.

The system combines all known advantages from a hydraulic torque tool system with the technology and advantages available from a modern servo based electrical controlled drive system. The included class 4 and class 2 interface sockets are easy to change on deck prior to deployment. The control system will automatically, detect socket and tool gear ratio and automatically switch between Low torque and High torque mode. The different sockets will automatically interface the gear system to utilize the optimal gear ration and power/speed utilization. The ELTT is designed for operation on ROV's with minimum 5-10A 110 VAC of continuous power available. Maw allowed power consumption can be limited in the ELTT control system setup. Max continuous current consumption is 20A. The tool communicates through RS232 protocol. The ELTT is connected to the ROV thru a 3,5mtr. oil filled yellow umbilical connected to an electrical power control module mounted on the ROV

The system is delivered in an aluminum transport box size 1182x782x500 for onshore and offshore handling.

*RS485 Optional

2,7kNm Torque Tool Kit